

CNNs for Fault Detection: a Wind Turbine Use Case

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- 1) CNNs for Scalable Fault Detection: a Wind Turbine Use Case (Lilach, 29.4.2021).
- 2) Transfer Learning Approaches for Fault Detection (Jannik, 6.5.2021).



Lilach Goren Huber



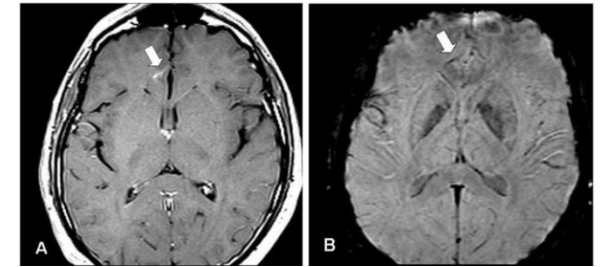
Markus Ulmer



Jannik Zraggen

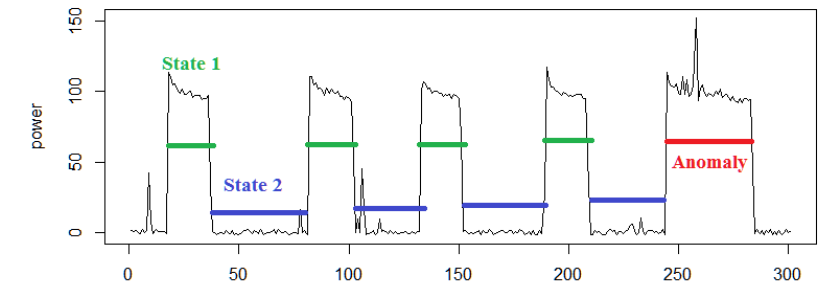
Fault Detection

- Anomaly detection: detect deviations from a familiar pattern → **anomaly score**.
- Fault detection: detect early patterns of deviations from normal behavior of machines → **Health Index**.
- Common machine data: multivariate time series.



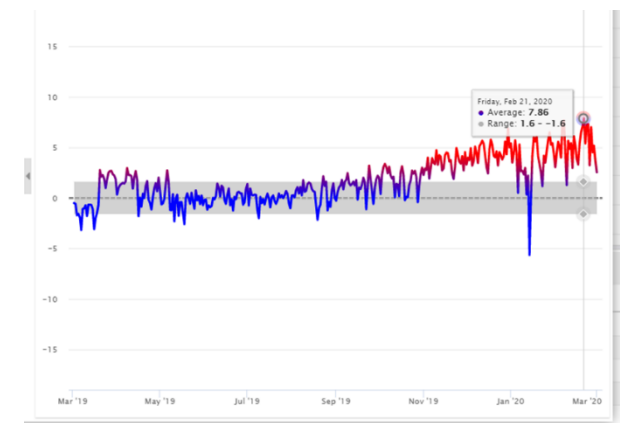
Complexities

- Anomalies are **rare** → class imbalance
- **Unknown** fault nature (time dependence, distribution)
- **Diversity** of anomaly classes/types (abrupt, slow degradations, point anomalies, different severity)



Challenges

- Threshold setting → False positives vs. Missed detections.
- Model evaluation.
- Detection + Explanation => diagnostics.
- Noise resilience under diverse operating conditions.

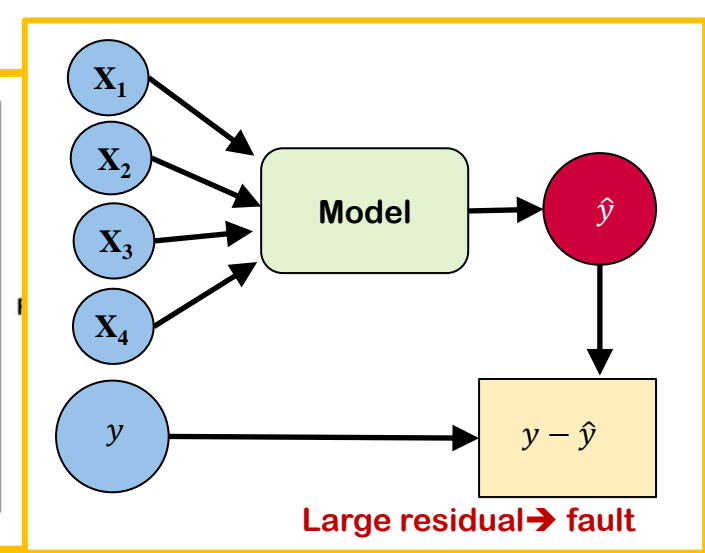
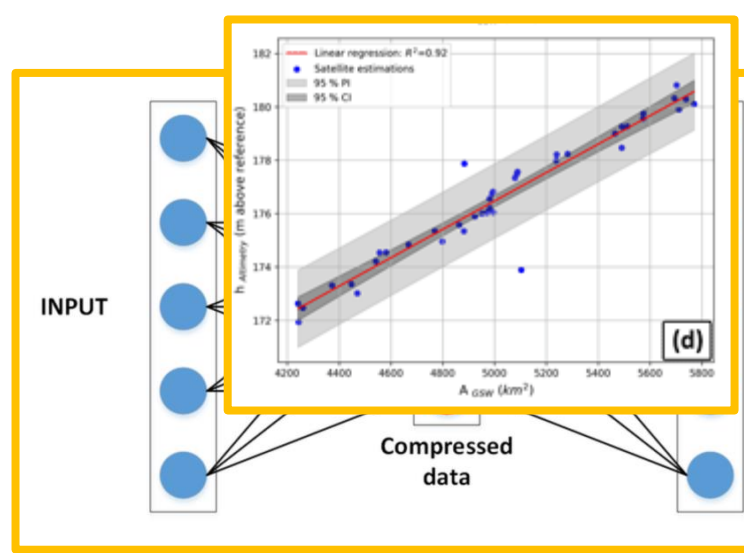
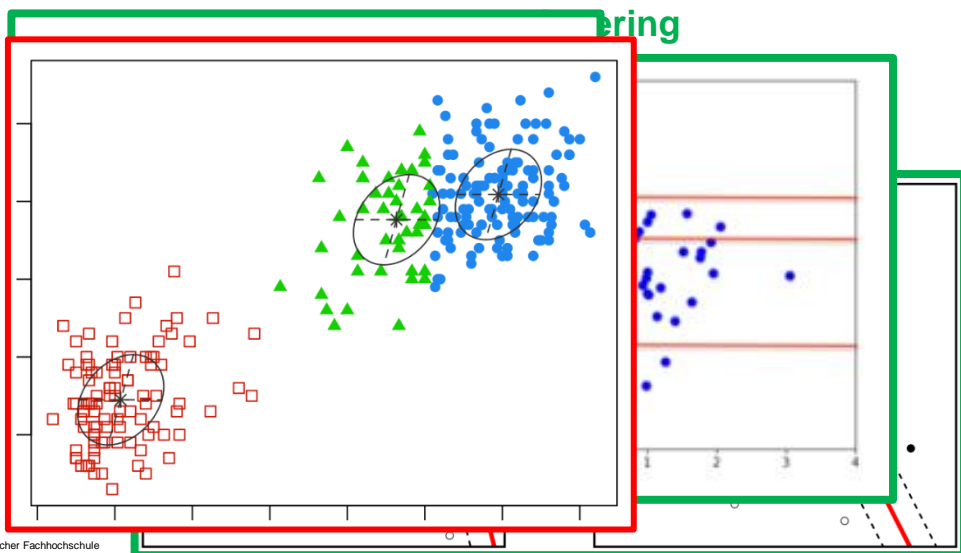
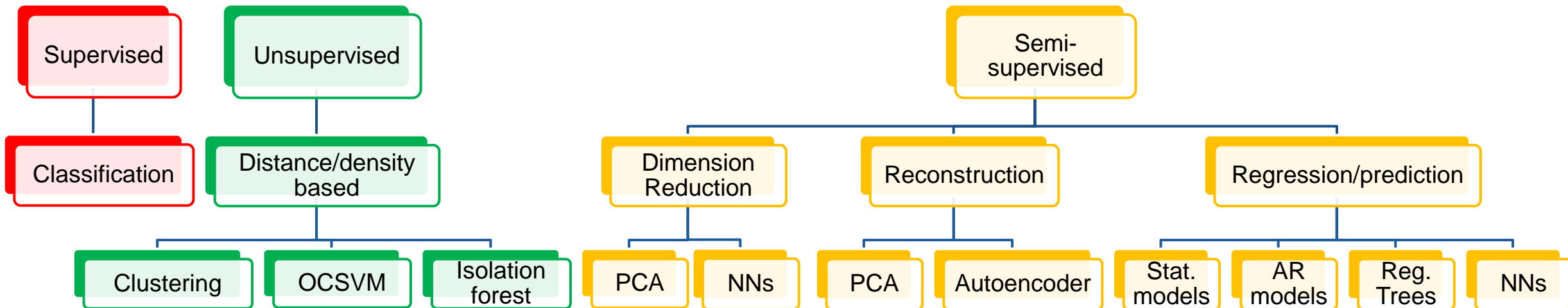


Anomaly Detection

Need labeled faults

Few clear outliers

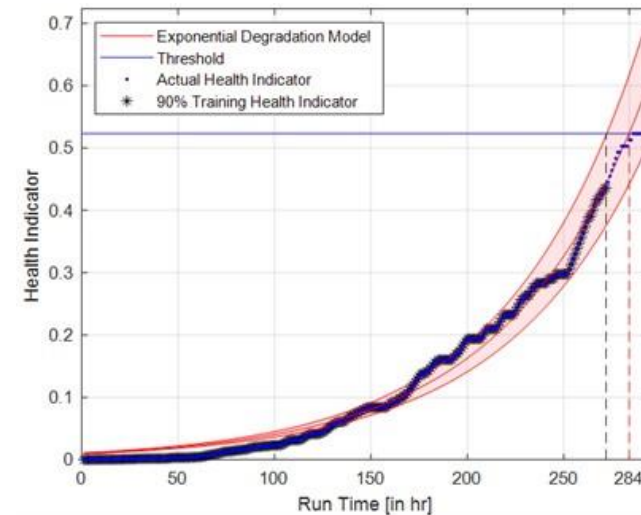
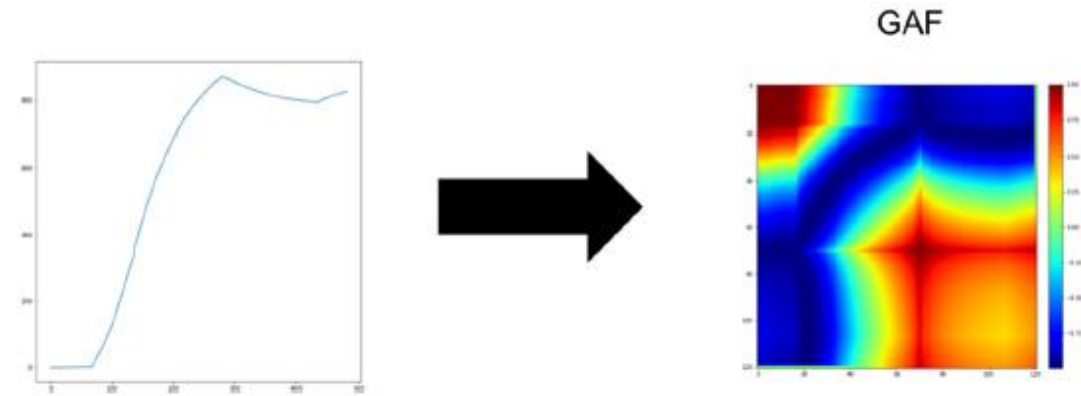
Train on healthy data



Trends in Fault Detection

Academic Research

- Method driven → classification mainly
- Encode ts data as images → limited applicability.
- RUL predictions (simulated data)
- Transfer Learning/ Domain Adaptation
- Hybrid models (physics + ML)
- Interpretability («XAI»)



Trends in Fault Detection

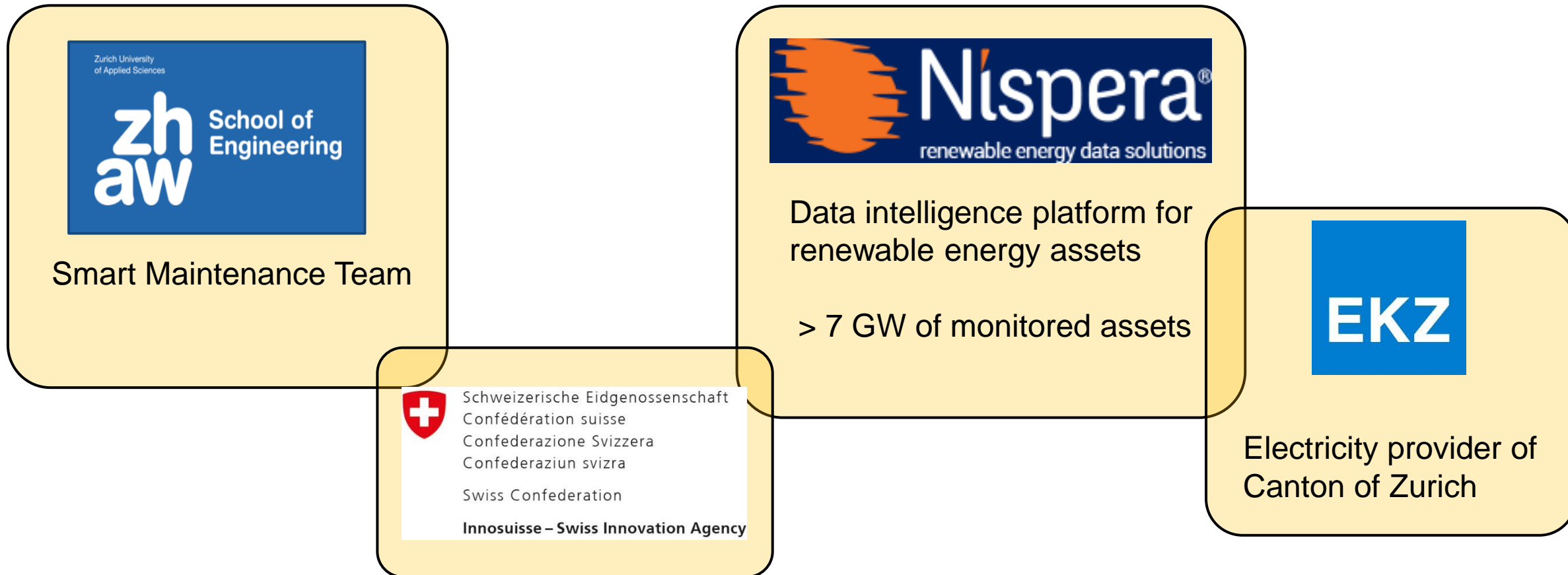
Academic Research

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- Hybrid models (physics + ML)
- Interpretability («XAI»)

Practical R&D

- Use existing data (little, no faults, low freq)
- How to set robust thresholds?
- How to evaluate algorithms without labels?
- How to scale up algorithms (data selection, run times)?
- Robustness under changing conditions.
- Diverse operating conditions (TL/DA?)

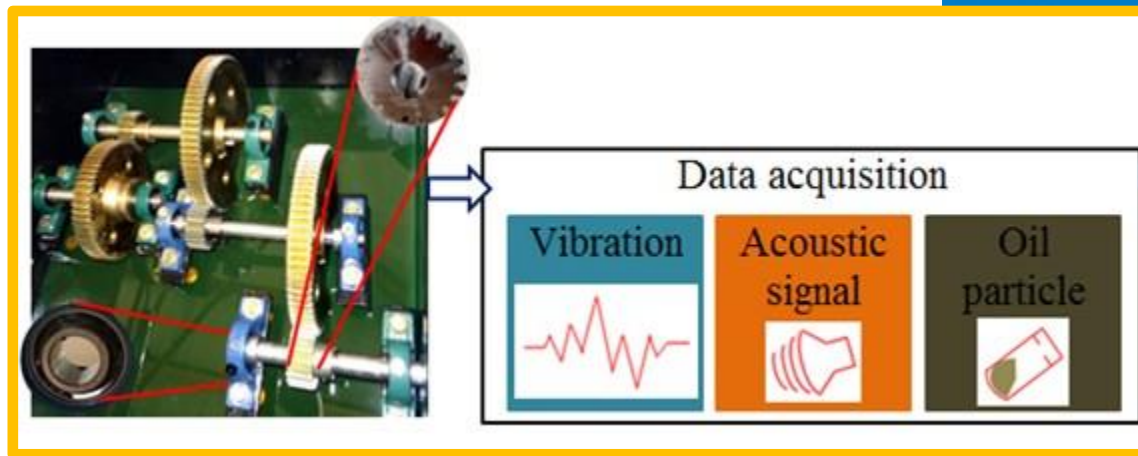
Who are we?



Intelligent fault detection and diagnosis algorithms for wind turbines

<https://nispera.com/solutions/predictive-maintenance>

Added Value for Park Operators



Original Equipment Manufacturer (OEM):

- Designated Condition Monitoring hardware.
- High frequency data.
- Use for design improvement.

Not accessible for operators/owners.

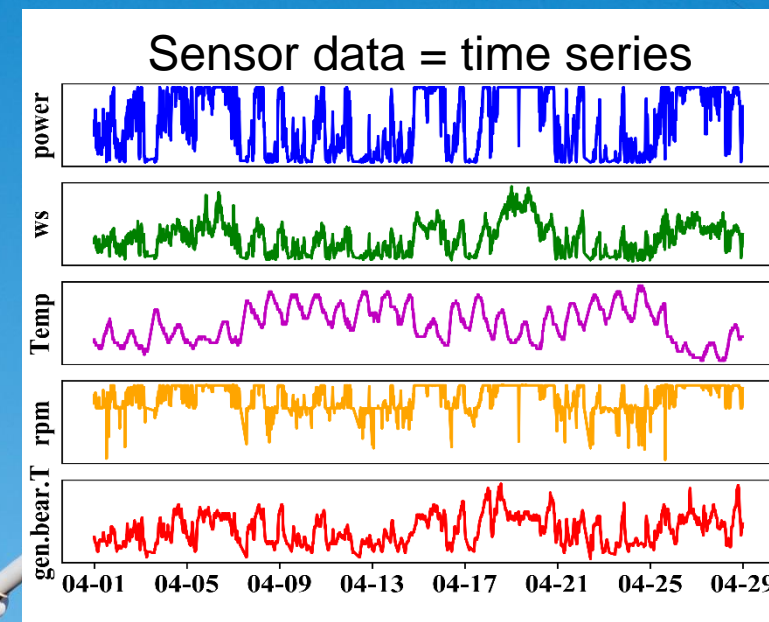
Designated Condition Monitoring Systems are too expensive

Added Value for Park Operators

Cost effective solution:

- Use available data.
- No need for additional hardware.

10-minute averaged
SCADA data is
already stored.



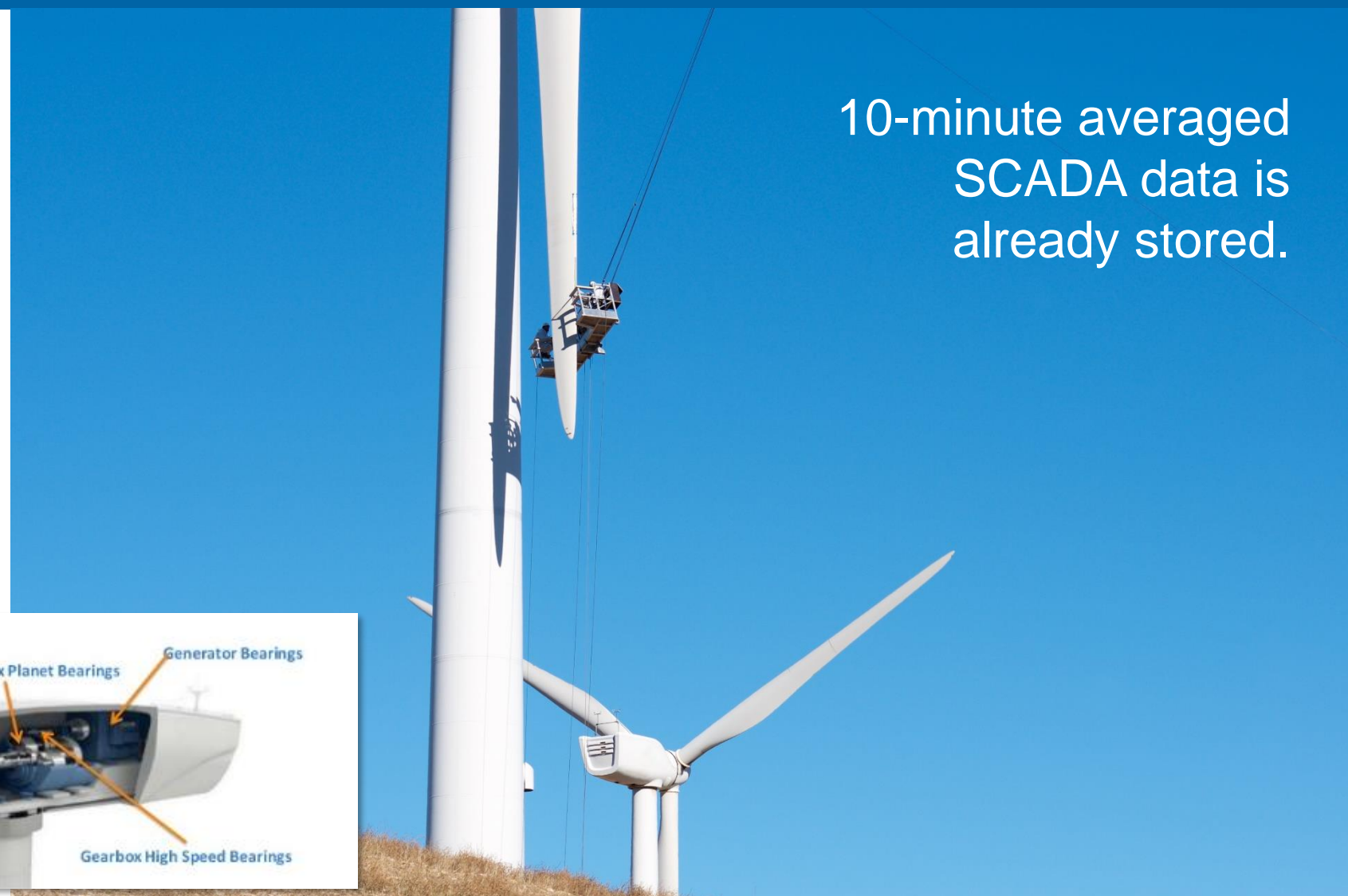
Challenge

High performance fault detection with existing data

10-minute averaged
SCADA data is
already stored.

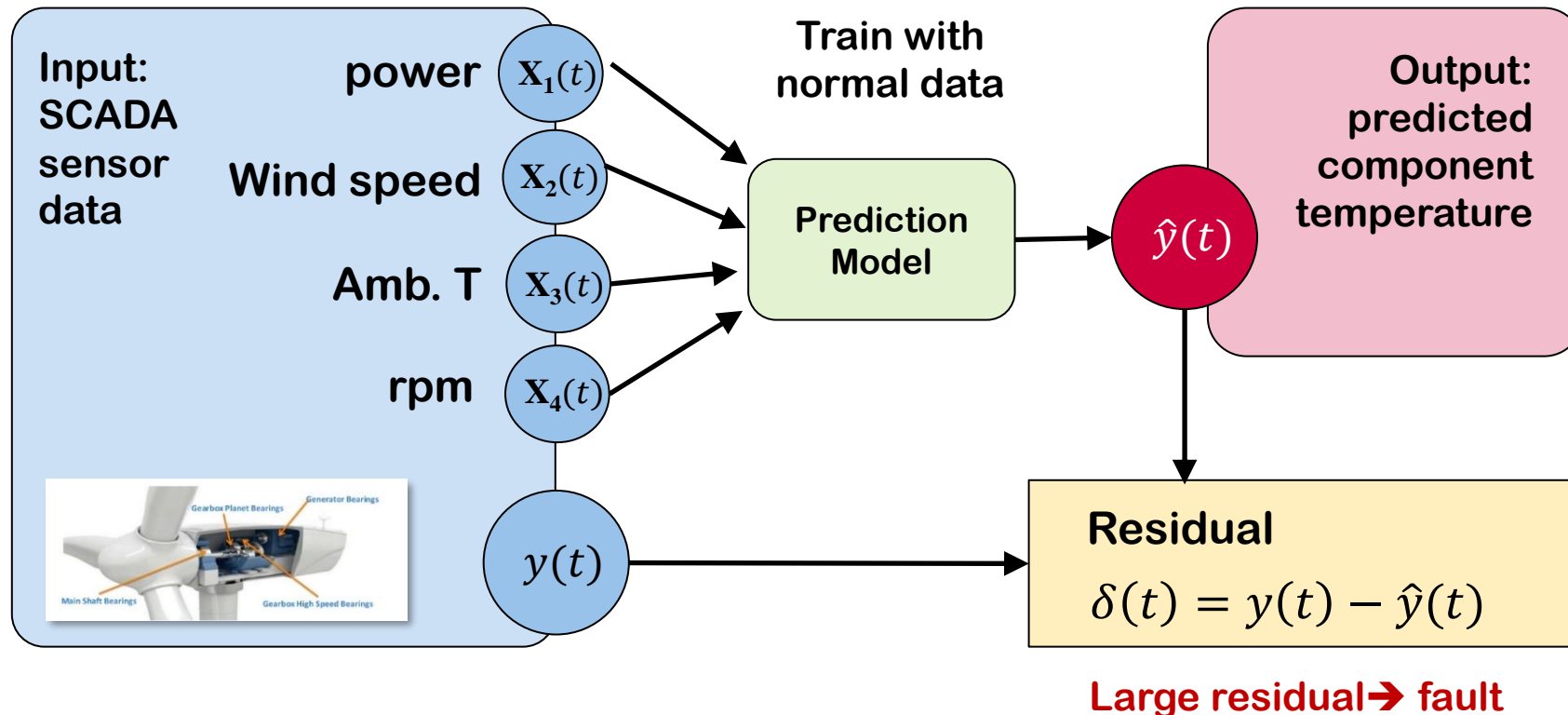
Practical solution:

- Detect early
- Accurately
- Diverse Fault types
- Transferable
- Scalable



Semi-supervised Anomaly Detection

- ✓ Faults are rare and unique → use only healthy data for training, detect anomalies online.
- ✓ Fault localization → regression

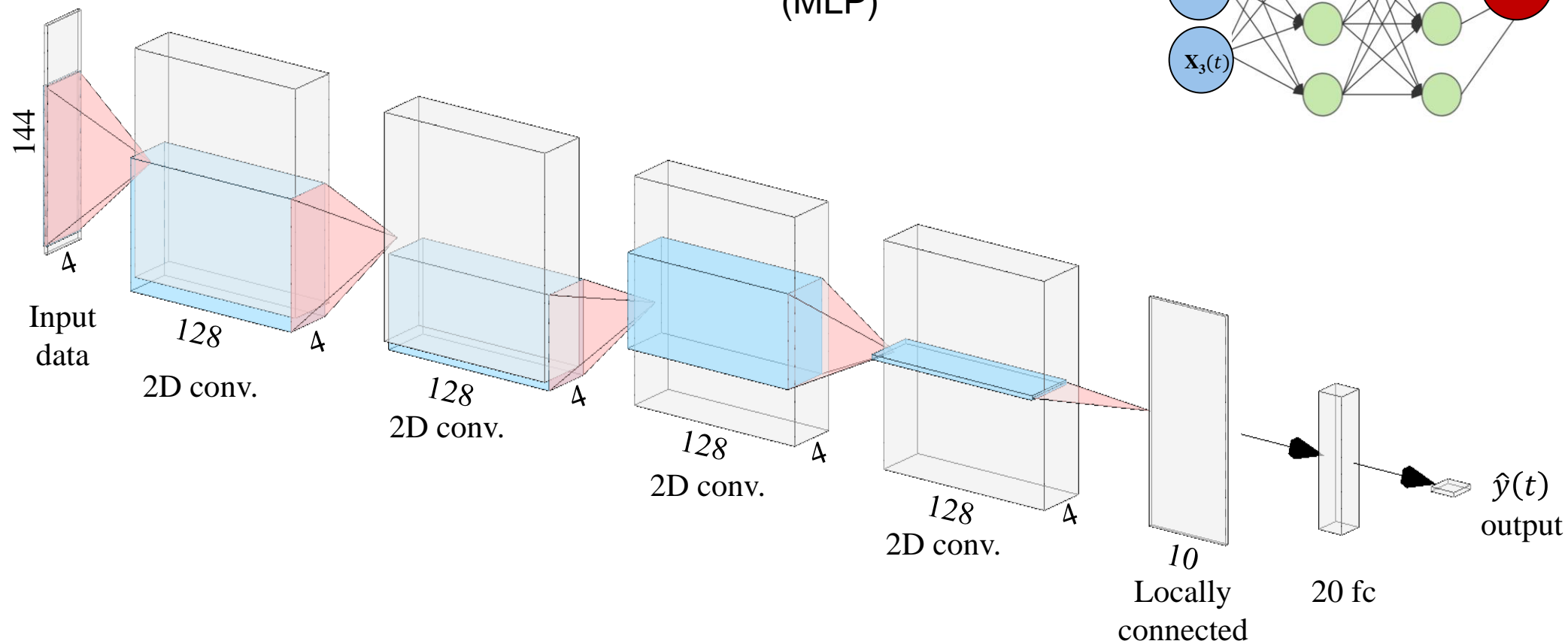


Prediction model

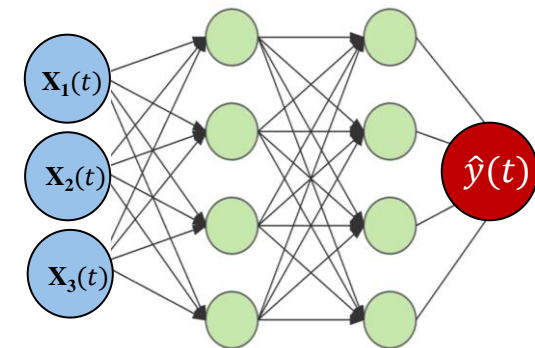
Single Output CNN

- ✓ Learn time dependent patterns → CNN

$$\begin{aligned} &x_1(1) \cdots x_1(t) \\ &x_2(1) \cdots x_2(t) \\ &x_3(1) \cdots x_3(t) \\ &x_4(1) \cdots x_4(t) \end{aligned}$$



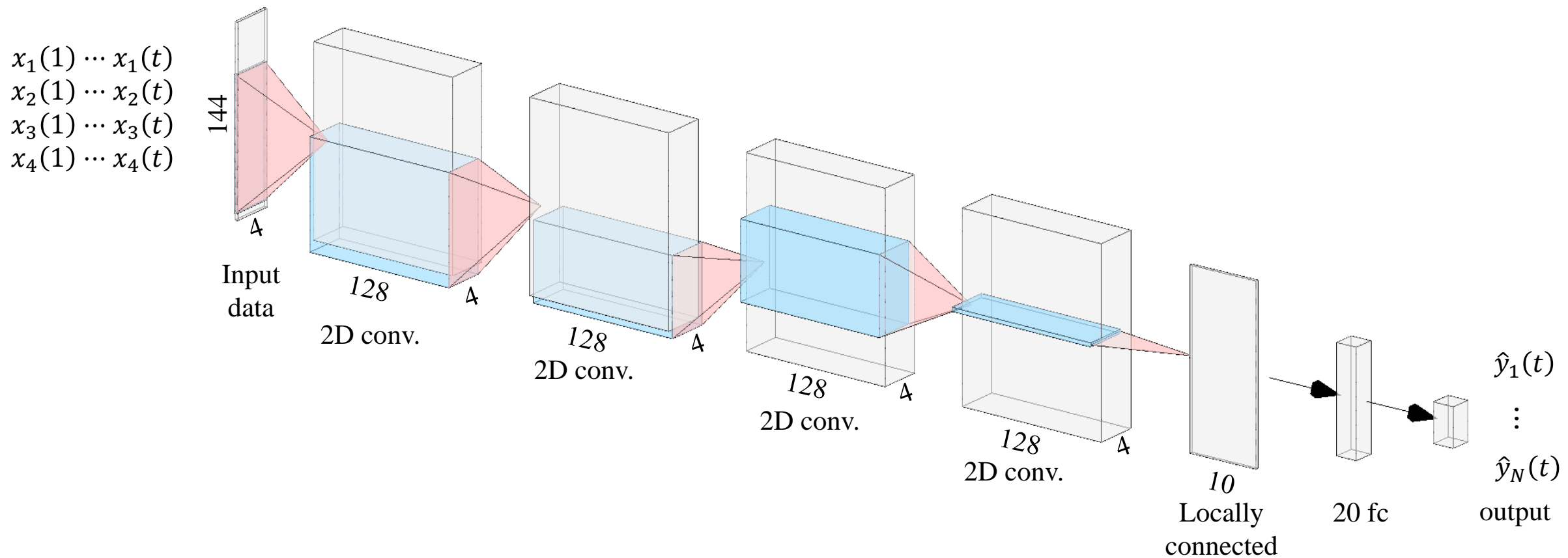
Commonly used:
Multi Layer Perceptron
(MLP)



Prediction Model

Multi-Output CNN (CNNm)

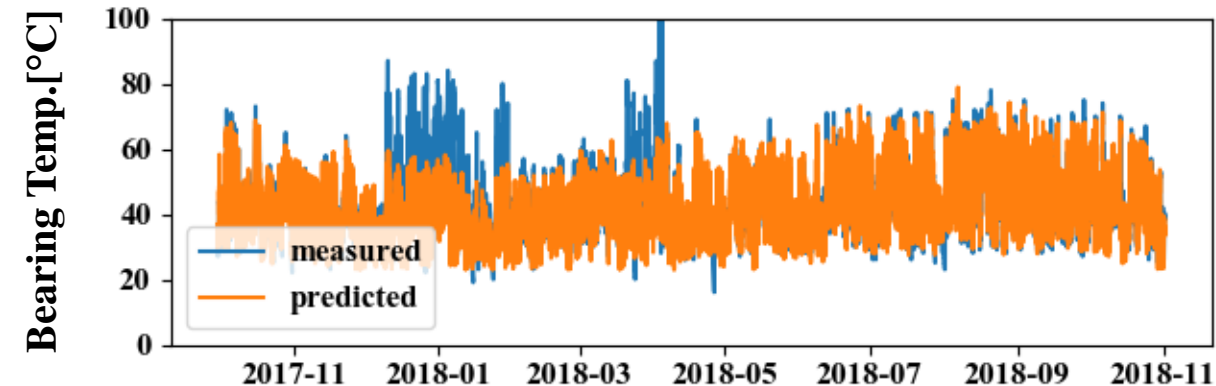
- ✓ Diverse fault types → multi-target regression



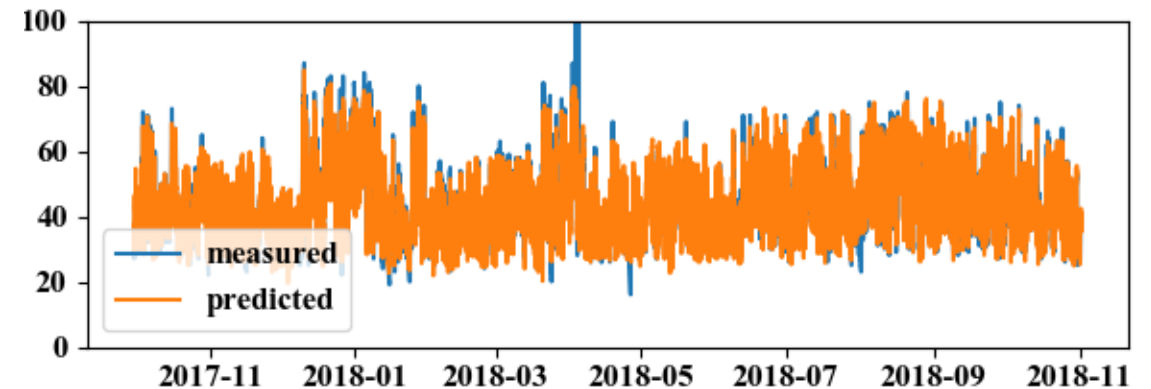
Model Evaluation and Selection

- Regression models: metric = prediction error MSE.
- AD: training on healthy data → we can only evaluate prediction error and minimize it.
- **Problem: model selection.** reducing the error on the healthy data does not imply increased error for fault data.
- Example: we can select a predictor with perfect correlation to the target. We then have good predictions also during abnormalities.

Without nacelle T as input



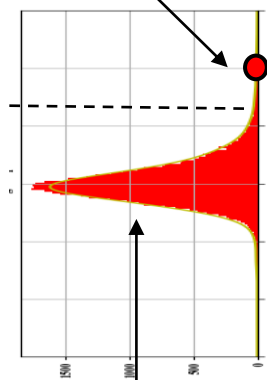
With nacelle T as input



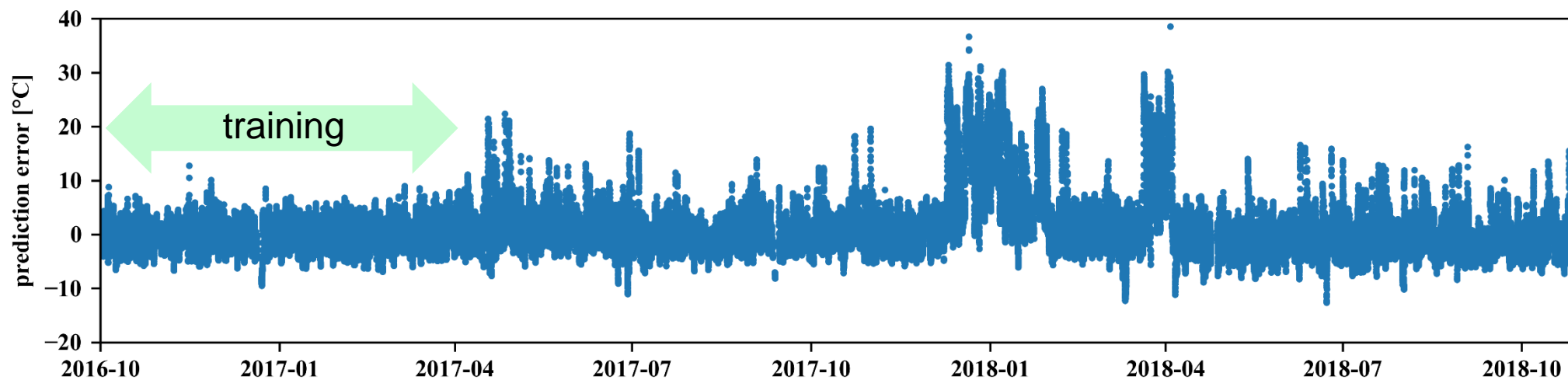
→ select a minimal set of «exogenic» predictors.

Over fitting

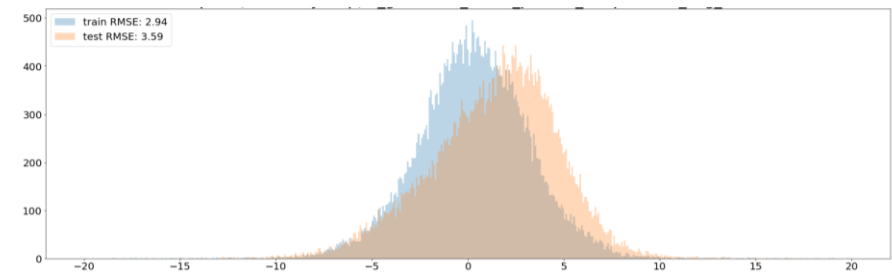
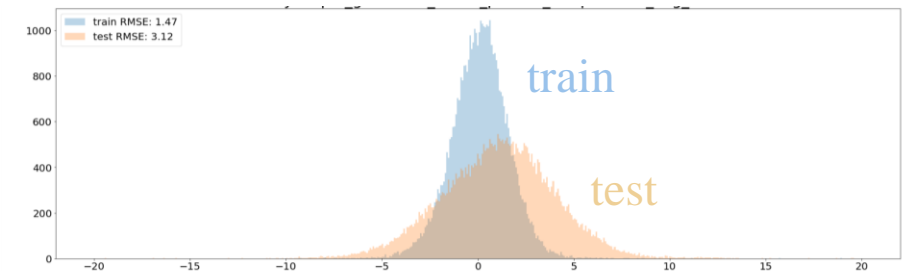
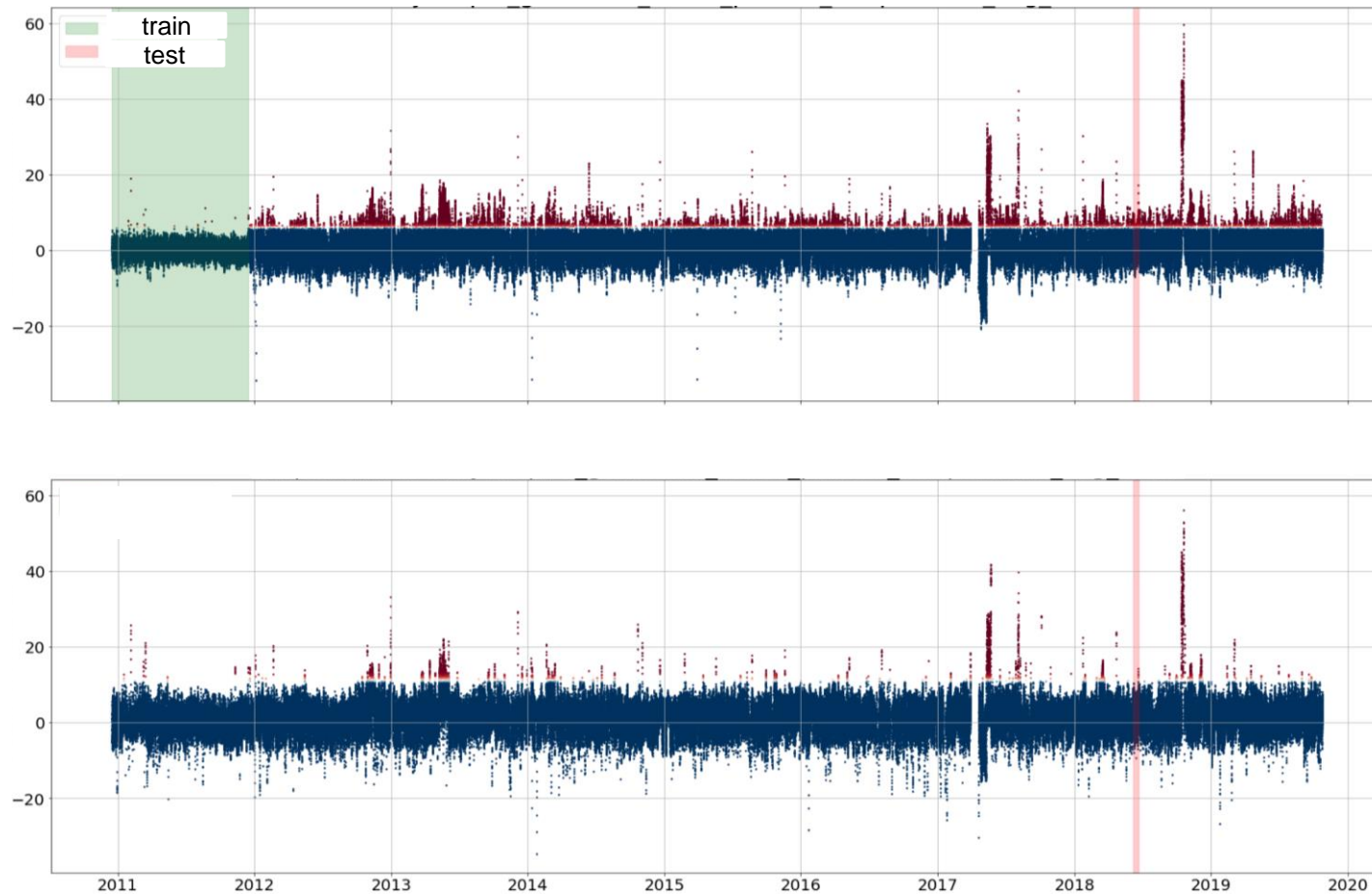
prediction



training



Over fitting

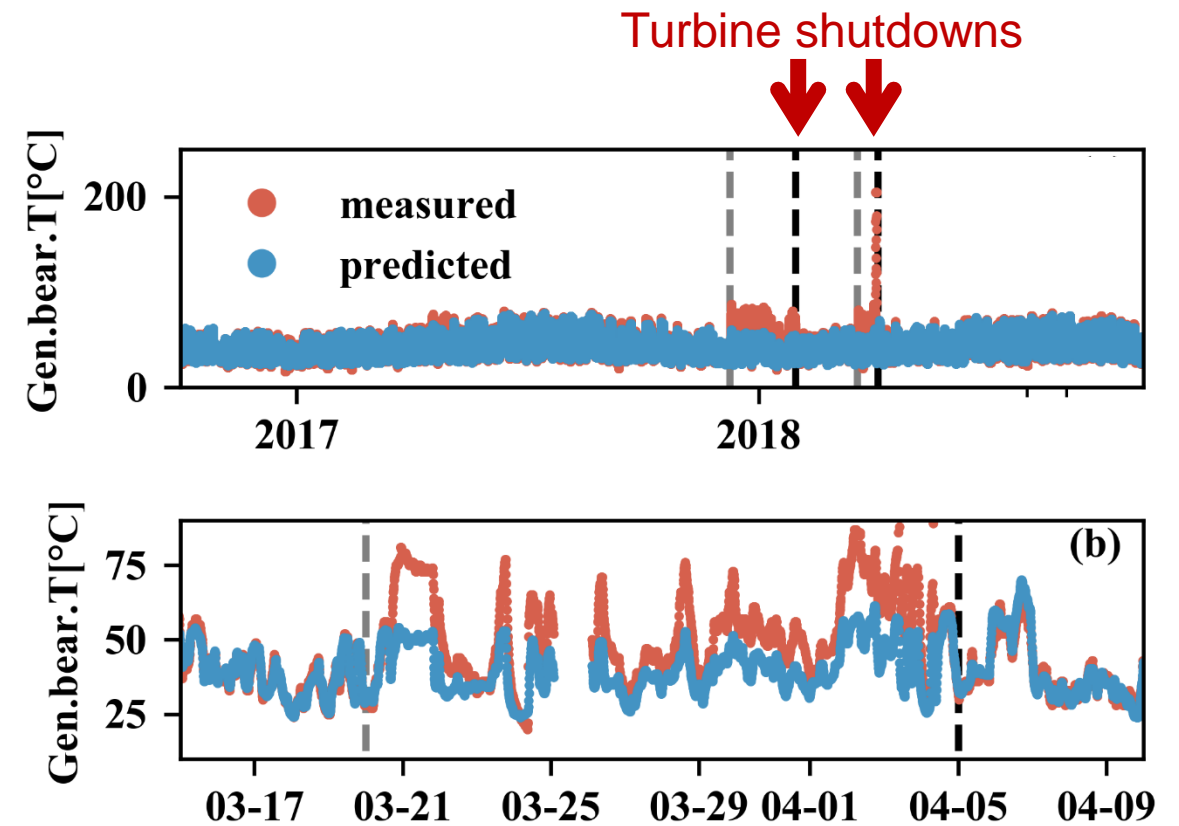


Over fitting:
Prediction errors at **testing** do not grow
training get smaller
→ False positives.

Example

Detection of Abrupt Faults

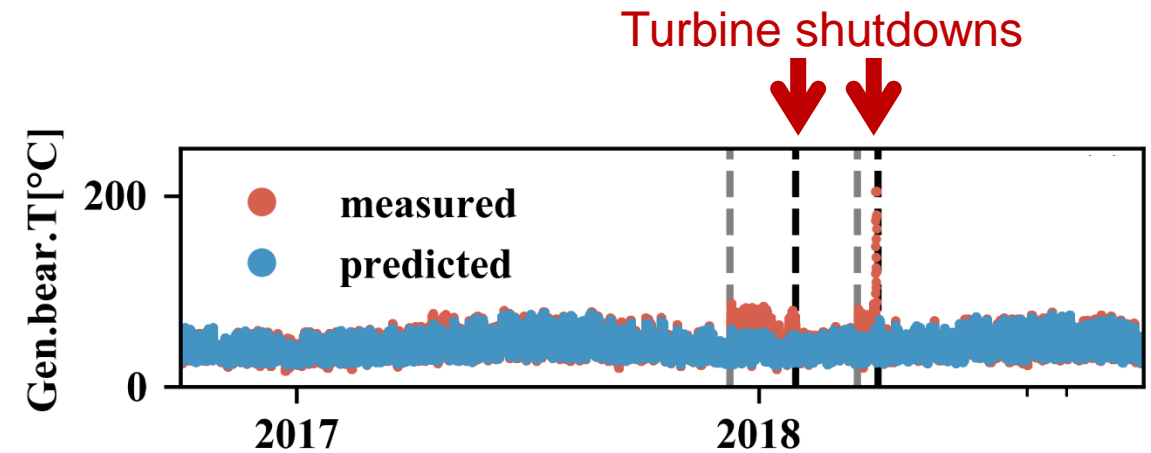
Turbine A_0
Abrupt faults in the generator bearing



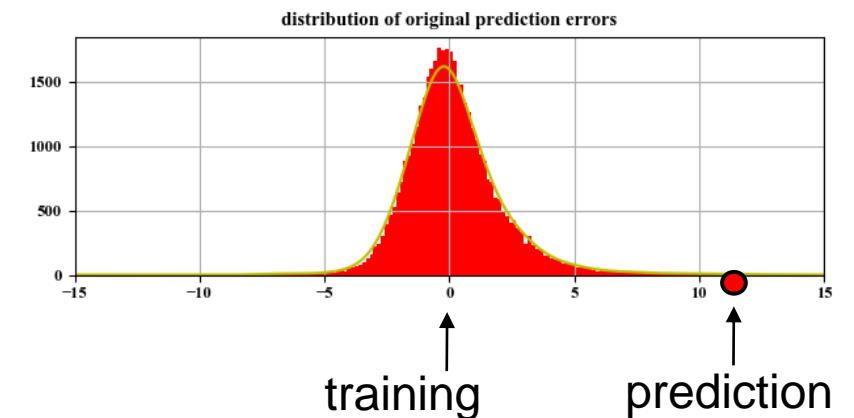
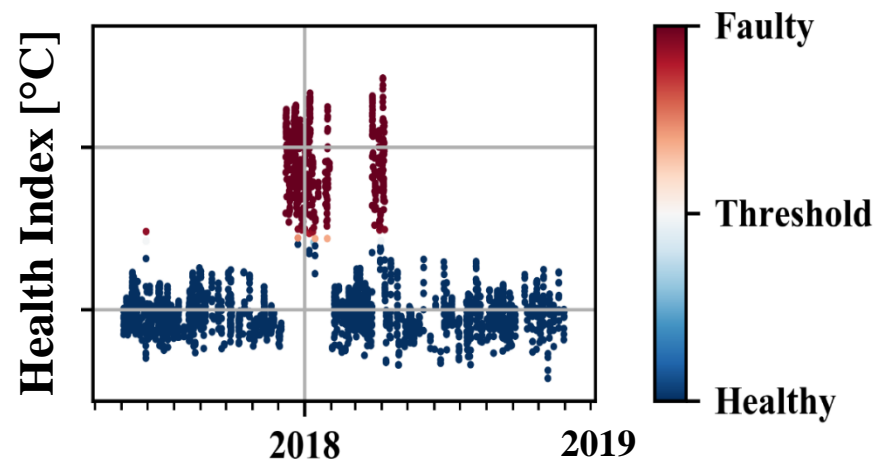
Results

Residuals and Health Index: Abrupt Faults

Turbine A_0
Abrupt faults in the generator bearing

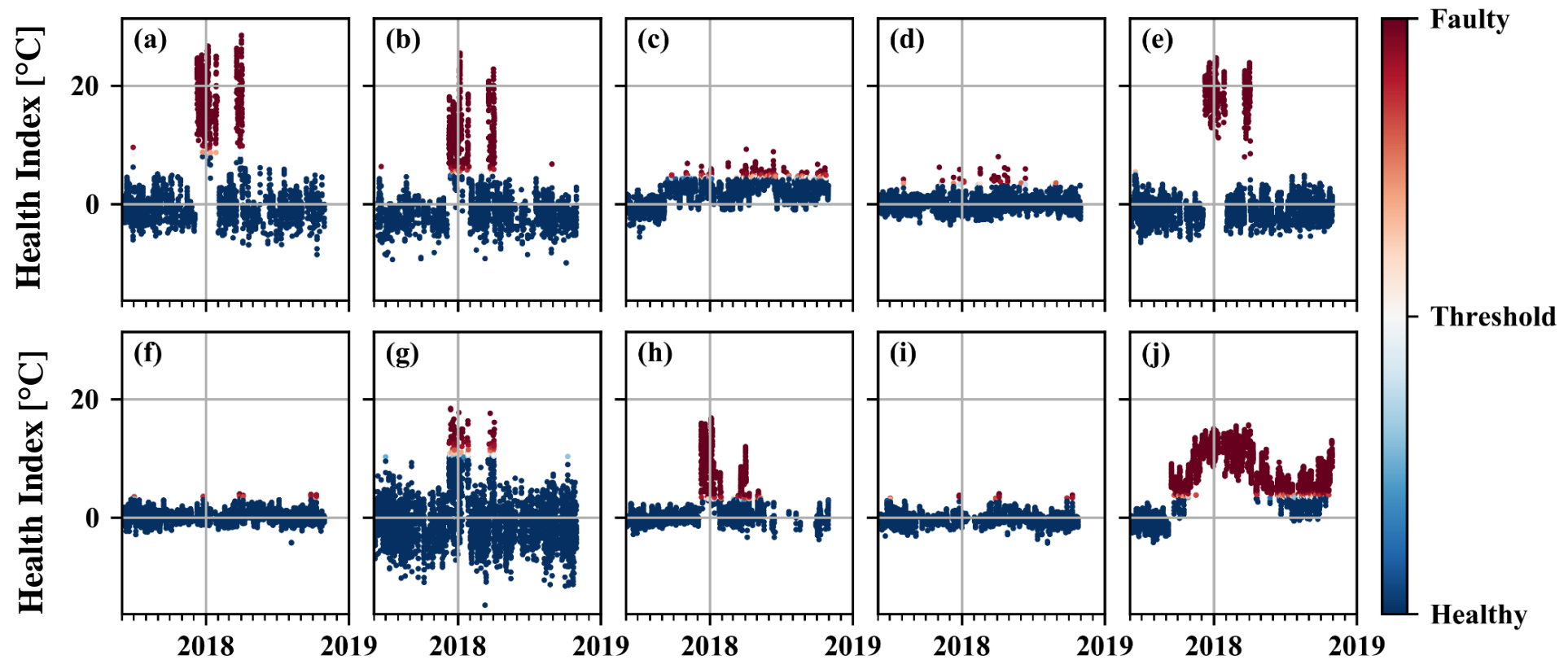


$$\delta(t) = y(t) - \hat{y}(t) \longrightarrow \text{Health Index}$$



Results

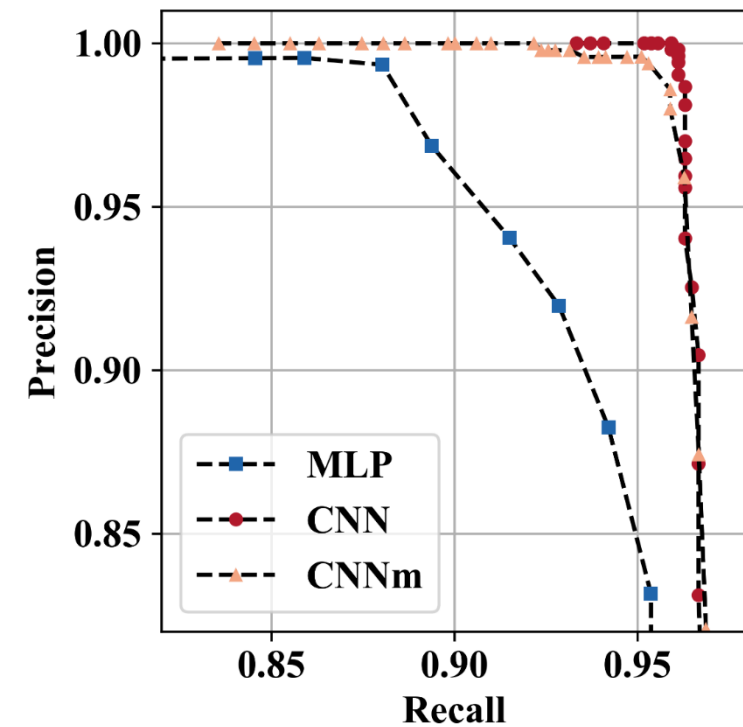
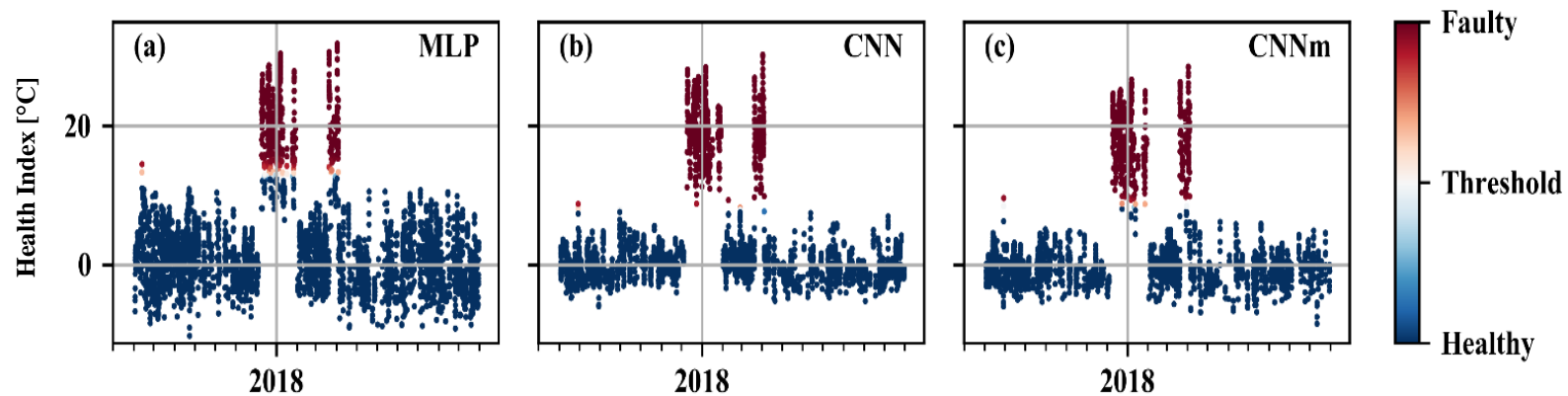
Health Indices with Multi-output CNN



(a) Generator bearing (b) stator phase (c) gearbox bearing (d) gearbox oil (e) slip ring
(f) rotor spinner (g) grid transformer (h) controller top (i) controller hub (j) hydraulic oil.

Results

Model Comparison: Abrupt Faults



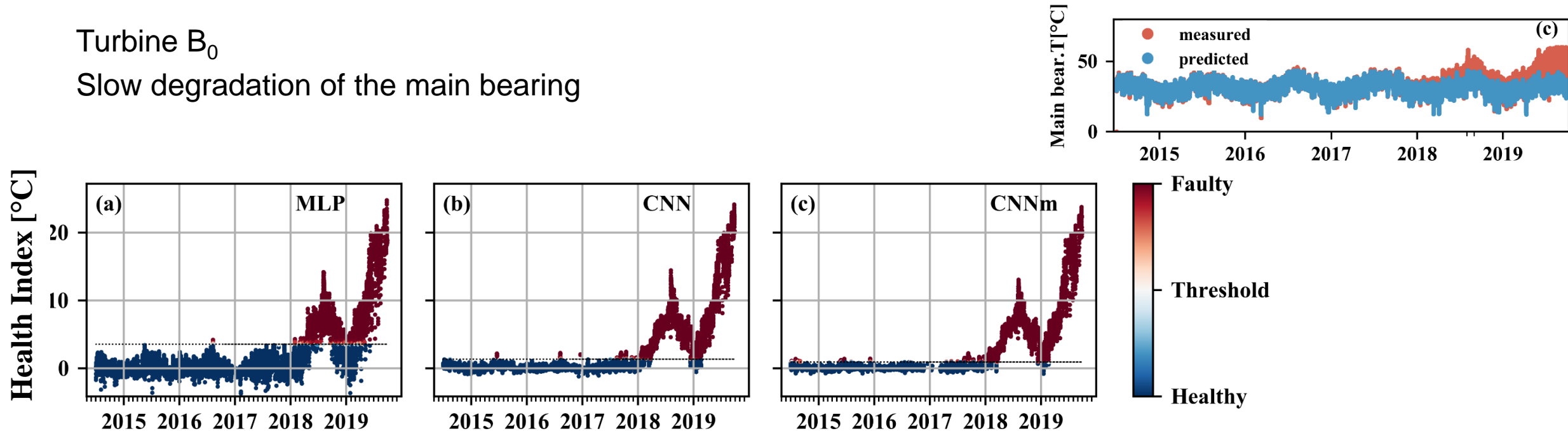
Both CNNs perform better than the MLP

Results

Model Comparison: Slow Degradation

Turbine B₀

Slow degradation of the main bearing

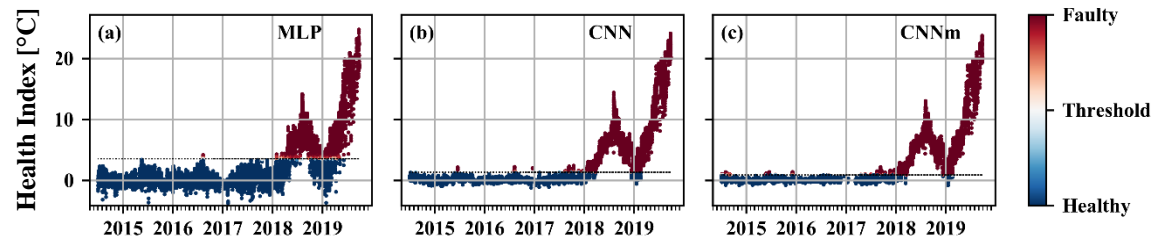


Model	First detection ($\alpha=0.0001$)	First detection high confidence
MLP	16.10.17 2:00	25.4.18 00:00
CNN	15.8.17 17:00	10.9.17 19:00
CNNm	15.8.17 17:00	9.9.17 14:00

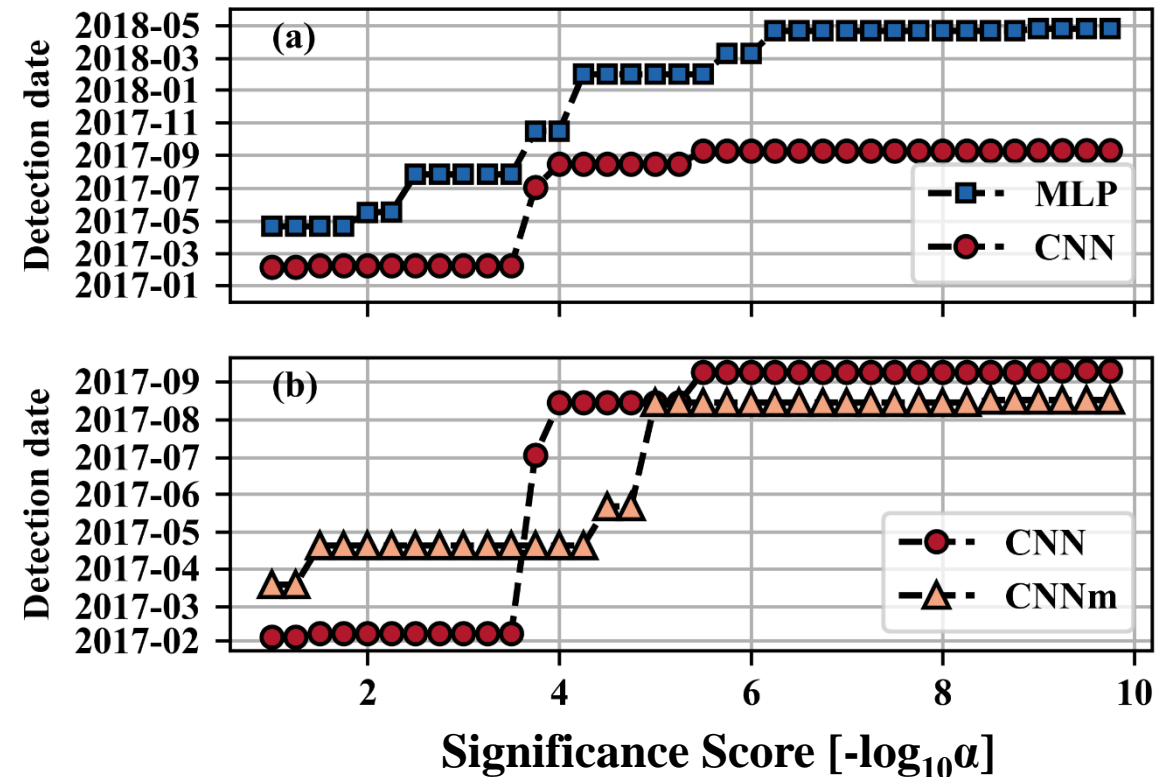
- ✓ CNN detects 2 months earlier than MLP.
- ✓ CNNm detects even earlier than CNN.

Results

Sensitivity Analysis: Slow Degradation



Modify the detection threshold and calculate the date of first detection:



Ulmer, Markus, et al. "Early fault detection based on wind turbine scada data using convolutional neural networks." *5th European Conference of the Prognostics and Health Management Society*, 2020.

The CNNm is more robust against threshold selection

Scaling up fault detection algorithms

Motivation for transfer learning

- New turbines/ farms.
- New operational conditions.
- Speed up fleet-wide detection.



Can we train on one turbine and predict on another?

Solution

Cross-Turbine Training Scheme

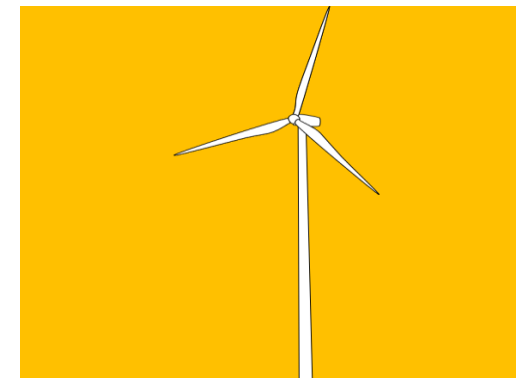
Goal: predict faults on turbine **T**.

Problem: only **3M** data from **T**.



Source Turbine **S**

Available healthy data: **9 Months**



Target Turbine **T**

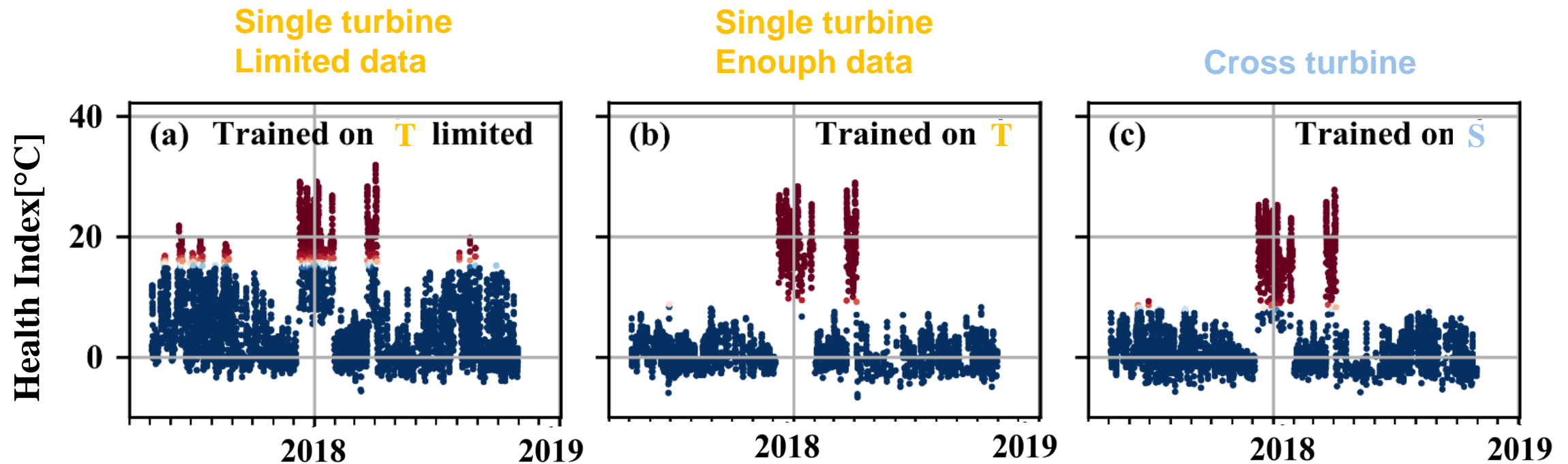
Available healthy data: **3 Months**

Simple Solution:

- Train CNN on **9M** from turbine **S**.
- Predict \hat{y}_t for new data from **T**.
- Train a regression model $y_t \sim \hat{y}_t + X_t$ on **3M** from **T**
- Adapt new predictions on **T** using the same regression.

Solution

Cross-Turbine Training Scheme

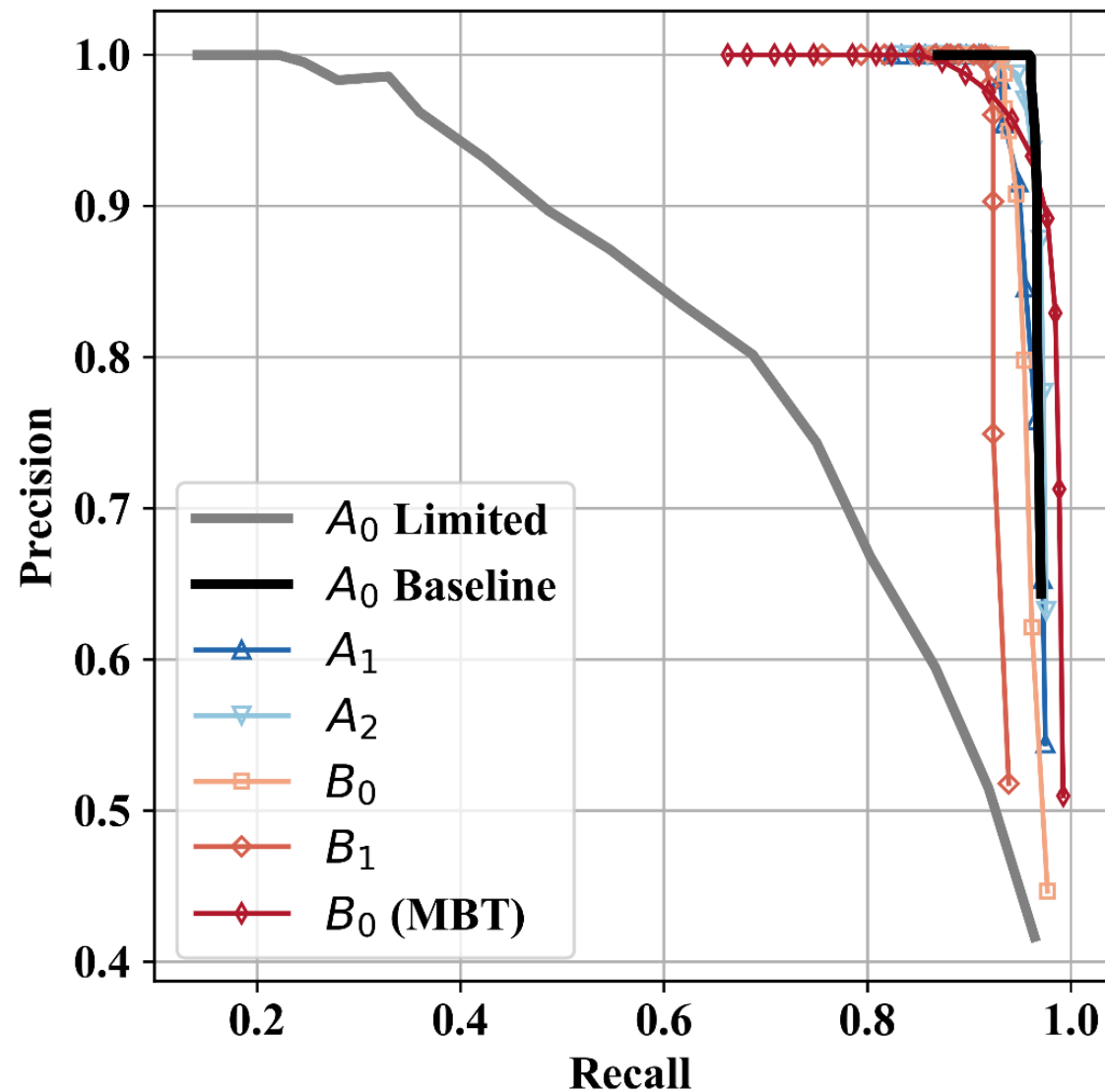


Cross-turbine training scheme allows early fault detection with scarce data

Results

Source domain comparison: abrupt fault

Ulmer, Markus, et al. "Cross-turbine training of convolutional neural networks for SCADA-based fault detection in wind turbines." *Annual Conference of the PHM Society.*, 2020.



Summary

- Fault detection of rare and diverse fault types → semi-supervised AD
 - Easy fault localization → regression
 - Robust capturing of time dependent patterns → CNNs
 - Scalable multi-component detection → multi-output CNN.
 - Robust threshold setting → use error distributions for anomaly scores.
 - Model evaluation → MSE not enough.
-
- Scarce data → TL approaches.
 - Preliminary: LR-based cross turbine training scheme with promising results.
 - Next week: overview of TL approaches, comparison of selected solutions.